FLAVIO ANTONIO VAZQUEZ

UPZMG  CINEMATICA DE ROBOTS

MATRICES HOMOGENEAS

# Matrices homogéneas:

1:

**X=60® Y=70® Z=10®**

**(XY)(Z) R=**

2:

**X=40® Y=10® Z=50®**

**(XY)(Z)**

3:

**X=42® Z=18® X=30®**

**(XZ)(X) R=**

4:

**X=30® Z=10® Y=30®**

**(XZX)(R) R=**

4:

**X=30® Z=10® Y=30®**

**(XZX)(R)**